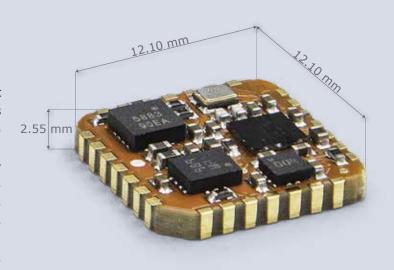
# MTi-2

- Miniature form factor (12x12 mm)
- Easy integration
- Development Kit available

The MTi-2 is a self-contained Vertical Reference Unit (VRU) as a 12.1 x 12.1 mm module. The Xsens optimized strapdown algorithm (AttitudeEngineTM) performs high-speed dead-reckoning calculations at 1 kHz allowing accurate capture of high frequency motions. Xsens' industry-leading sensor fusion algorithm provides high accuracy and sensor auto-calibration in a cost-effective module for a wide range of (embedded) applications. It relieves users from the design, integration and maintenance of gyroscopes, accelerometers and other sensors.

The MTi-2 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.



- 3D models available on request
- Available at DigiKey, Mouser, Farnell, Arrow and local distributors

# **Sensor fusion performance**

Roll, Pitch	0.5 deg RMS
Yaw/Heading	unreferenced, low drift
Strapdown Integration (SDI)	Yes

## **Gyroscope**

Standard full range —————	2000 deg/s
In-run bias stability	6 deg/h
Bandwidth (-3dB)	230 Hz
Noise Density	0.003 °/s/√Hz
g-sensitivity (calibr.)	0.001 º/s/q

#### Accelerometer

Standard full range ——————	16 g
In-run bias stability	40 µg
Bandwidth (-3dB)	230 Hz
Noise Density	70 μg/√Hz

#### Magnetometer

Standard full range	+/- 8 G
Total RMS noise	0.5 mG
Non-linearity	0.2%
Resolution	0.25 mG

## **GNSS Receiver**

GNSS receiver interface	n/a
GNSS precision	n/a
RTCM input nort	n/a

#### **Barometer**

Barometer interface	n/a
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## **Mechanical**

IP-rating	IPOO
Operating Temperature ———	-40 to 85 °C
Casing material	PCB
Mounting orientation	No restriction, full 360° in all axes
Dimensions	12.1 x 12.1 x 2.55 mm
Connector	SMD, footprint compatible with
	JEDEC PLCC-28
Weight	0.6 g
Certifications	CE, FCC, RoHS

#### **Electrical**

Input voltage	2.8 to 3.6V
Power consumption (typ)	<100 mW @ 3V

### Interfaces / IO

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Interfaces	UART, SPI, I <sup>2</sup> C
Sync Options	Yes
Protocols	Xbus
Clock drift	10 ppm or external
Output Frequency	Up to 1 kHz
Built-in-self test	Gyr, Acc, Mag

#### **Software Suite**

GUI (Windows/Linux)	MT Manager Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab, Nucleo,
	public source code
Drivers	LabVIEW, ROS, GO
Support	BASE by XSENS: online manuals,
	community and knowledge base



